

**Script** generated by TTT

Title: Seidl: Virtual\_Machines (30.04.2013)

Date: Tue Apr 30 14:01:29 CEST 2013

Duration: 90:36 min

Pages: 34

The code for `return e;` corresponds to an assignment to a variable with relative address `-3`.

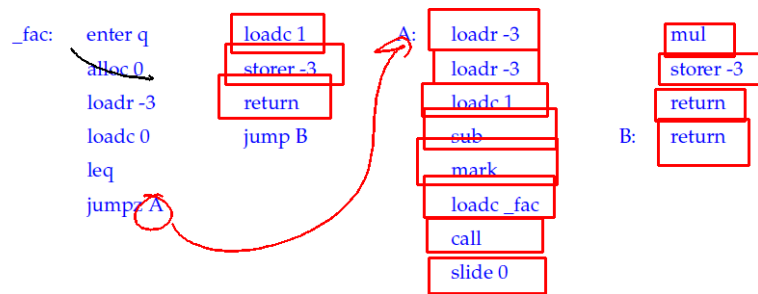
```
code return e; ρ = code e ρ
                  storer -3
                  return
```

**Example** For function

```
int fac (int x) {
  if (x ≤ 0) return 1;
  else return x * fac (x - 1);
}
```

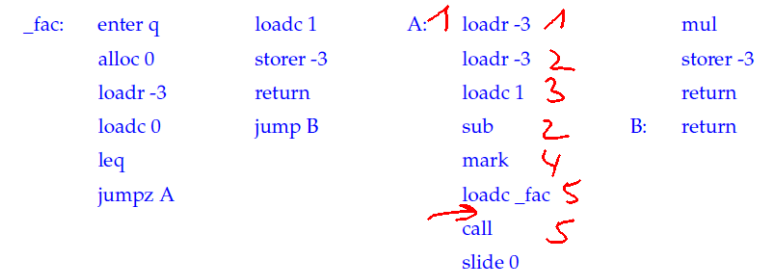
we generate:

96



where  $\rho_{fac} : x \mapsto (L, -3)$  and  $q = 1 + 5 = 6$ .

97



where  $\rho_{fac} : x \mapsto (L, -3)$  and  $q = 2 + 5 = 7$ .

97

## 10 Translation of Whole Programs

Before program execution, we have:

$$SP = -1 \quad FP = EP = 0 \quad PC = 0 \quad NP = MAX$$

Let  $p \equiv V\_defs \ F\_def_1 \dots F\_def_n$ , denote a program where  $F\_def_i$  is the definition of a function  $f_i$  of which one is called `main`.

The code for the program  $p$  consists of:

- code for the function definitions  $F\_def_i$ ;
- code for the allocation of global variables;
- code for the call `von main()`;
- the instruction `halt`.

98

Then we define:

```
code p  $\emptyset$  =   enter (k + 5)
                alloc (k + 1)
                mark
                loadc _main
                call
                slide (k + 1)
                halt
                _f1: code F_def1  $\rho$ 
                :
                _fn: code F_defn  $\rho$ 
```

where  $\emptyset \hat{=}$  empty address environment;  
 $\rho \hat{=}$  global address environment;  
 $k \hat{=}$  size of the global variables

99

## 10 Translation of Whole Programs

Before program execution, we have:

$$SP = -1 \quad FP = EP = 0 \quad PC = 0 \quad NP = MAX$$

Let  $p \equiv V\_defs \ F\_def_1 \dots F\_def_n$ , denote a program where  $F\_def_i$  is the definition of a function  $f_i$  of which one is called `main`.

The code for the program  $p$  consists of:

- code for the function definitions  $F\_def_i$ ;
- code for the allocation of global variables;
- code for the call `von main()`;
- the instruction `halt`.

98

Then we define:

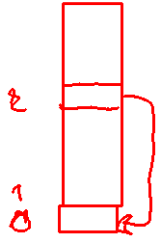
```
code p  $\emptyset$  =   enter (k + 5)
                alloc (k + 1)
                mark
                loadc _main
                call
                slide (k + 1)
                halt
                _f1: code F_def1  $\rho$ 
                :
                _fn: code F_defn  $\rho$ 
```

where  $\emptyset \hat{=}$  empty address environment;  
 $\rho \hat{=}$  global address environment;  
 $k \hat{=}$  size of the global variables

99

*k*  
*k+2*  
*k+3*  
*k+3*

Then we define:



```
code p  $\emptyset$  =
  enter (k + 3)
  alloc (k + 1)
  mark
  loadc _main
  call
  slide (k + 1)
  halt
  _f1: code Fdef1  $\rho$ 
  ⋮
  _fn: code Fdefn  $\rho$ 
```

where  $\emptyset \hat{=}$  empty address environment;  
 $\rho \hat{=}$  global address environment;  
 $k \hat{=}$  size of the global variables

## 10 Translation of Whole Programs

Before program execution, we have:

$$SP = -1 \quad FP = EP = 0 \quad PC = 0 \quad NP = MAX$$

Let  $p \equiv V\_defs \ F\_def_1 \dots F\_def_n$ , denote a program where  $F\_def_i$  is the definition of a function  $f_i$  of which one is called `main`.

The code for the program  $p$  consists of:

- code for the function definitions  $F\_def_i$ ;
- code for the allocation of global variables;
- code for the call `von main()`;
- the instruction `halt`.

*The null should reside in S[0]*

Then we define:

```
code p  $\emptyset$  =
  enter (k + 5)
  alloc (k + 1)
  mark
  loadc _main
  call
  slide (k + 1)
  halt
  _f1: code Fdef1  $\rho$ 
  ⋮
  _fn: code Fdefn  $\rho$ 
```

where  $\emptyset \hat{=}$  empty address environment;  
 $\rho \hat{=}$  global address environment;  
 $k \hat{=}$  size of the global variables

Then we define:

```
code p  $\emptyset$  =
  enter (k + 5)
  alloc (k + 1)
  mark
  loadc _main
  call
  slide (k + 1)
  halt
  _f1: code Fdef1  $\rho$ 
  ⋮
  _fn: code Fdefn  $\rho$ 
```

where  $\emptyset \hat{=}$  empty address environment;  
 $\rho \hat{=}$  global address environment;  
 $k \hat{=}$  size of the global variables

# The Translation of Functional Programming Languages

100

Haskell  
SIL/Ound

## 11 The language PuF

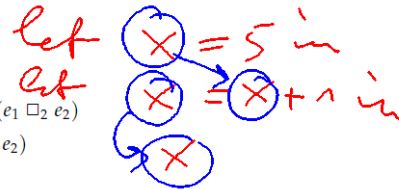
We only regard a mini-language PuF ("Pure Functions").

We do not treat, as yet:

- Side effects;
- Data structures.

101

A program is an expression  $e$  of the form:

$$\begin{aligned}
 e ::= & b \mid x \mid (\square_1 e) \mid (e_1 \square_2 e_2) \\
 & \mid (\text{if } e_0 \text{ then } e_1 \text{ else } e_2) \\
 & \mid (e' e_0 \dots e_{k-1}) \\
 & \mid (\text{fun } x_0 \dots x_{k-1} \rightarrow e) \\
 & \mid (\text{let } x_1 = e_1 \text{ in } e_0) \\
 & \mid (\text{let rec } x_1 = e_1 \text{ and } \dots \text{ and } x_n = e_n \text{ in } e_0)
 \end{aligned}$$


An expression is therefore

- a basic value, a variable, the application of an operator, or
- a function-application, a function-abstraction, or
- a let-expression, i.e. an expression with locally defined variables, or
- a let-rec-expression, i.e. an expression with simultaneously defined local variables.

For simplicity, we only allow `int` as basic type.

102

### Example:

The following well-known function computes the factorial of a natural number:

```

let rec fac = fun x → if x ≤ 1 then 1
                else x · fac (x - 1)

```

*let rec*

As usual, we only use the minimal amount of parentheses.

There are two Semantics:

**CBV:** Arguments are evaluated before they are passed to the function (as in SML);

**CBN:** Arguments are passed unevaluated; they are only evaluated when their value is needed (as in Haskell).

103

### Example:

The following well-known function computes the factorial of a natural number:

```
let rec fac = fun x → if x ≤ 1 then 1
                  else x · fac (x - 1)
in fac 7
```

↑   ↑

As usual, we only use the minimal amount of parentheses.

There are two **Semantics**:

**CBV**: Arguments are evaluated **before** they are passed to the function (as in SML);

**CBN**: Arguments are passed unevaluated; they are only evaluated when their value is needed (as in Haskell).

*miranda*

### Example:

The following well-known function computes the factorial of a natural number:

```
let rec fac = fun x → if x ≤ 1 then 1
                  else x · fac (x - 1)
in fac 7
```

As usual, we only use the minimal amount of parentheses.

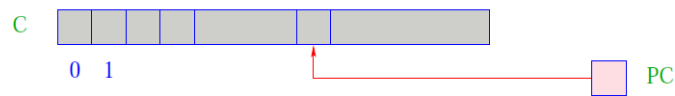
There are two **Semantics**:

**CBV**: Arguments are evaluated **before** they are passed to the function (as in SML);

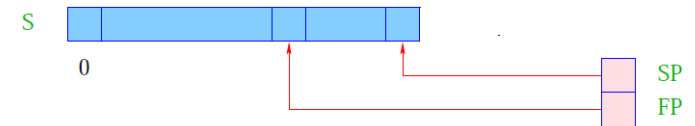
**CBN**: Arguments are passed unevaluated; they are only evaluated when their value is needed (as in Haskell).

## 12 Architecture of the MaMa:

We know already the following components:

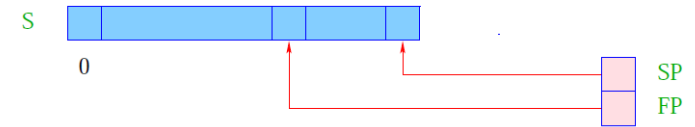
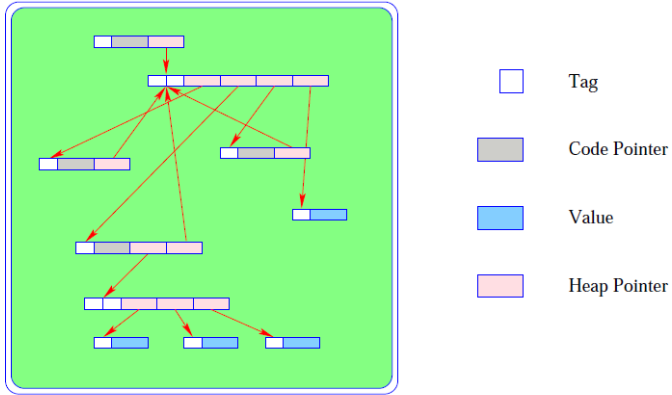


- C = Code-store – contains the **MaMa**-program; each cell contains one instruction;
- PC = Program Counter – points to the instruction to be executed next;



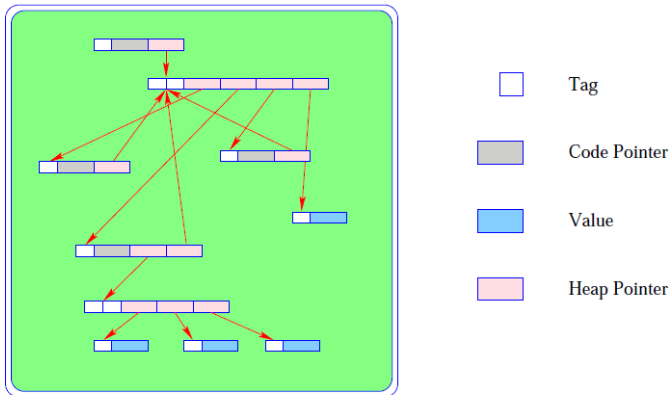
- S = Runtime-Stack – each cell can hold a basic value or an address;
- SP = Stack-Pointer – points to the topmost occupied cell; as in the **CMa** implicitly represented;
- FP = Frame-Pointer – points to the actual stack frame.

We also need a heap H:

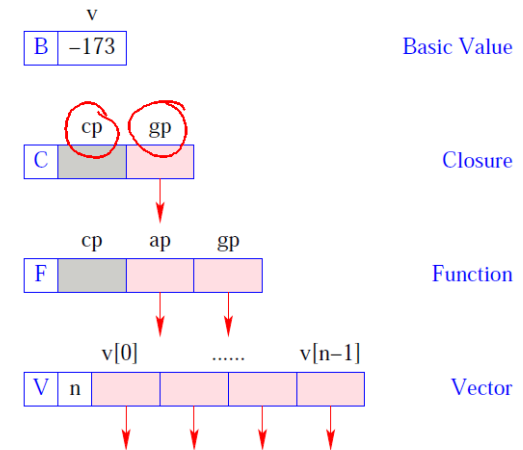


- S = Runtime-Stack – each cell can hold a basic value or an address;
- SP = Stack-Pointer – points to the topmost occupied cell; as in the CMa implicitly represented;
- FP = Frame-Pointer – points to the actual stack frame.

We also need a heap H:



... it can be thought of as an abstract data type, being capable of holding data objects of the following form:



The instruction  $\text{new}(tag, args)$  creates a corresponding object  $(B, C, F, V)$  in  $H$  and returns a reference to it.

We distinguish three different kinds of code for an expression  $e$ :

- $\text{code}_V e$  — (generates code that) computes the **V**alue of  $e$ , stores it in the heap and returns a reference to it on top of the stack (the normal case);
- $\text{code}_B e$  — computes the value of  $e$ , and returns it on the top of the stack (only for **B**asic types);
- $\text{code}_C e$  — does **not** evaluate  $e$ , but stores a **C**losure of  $e$  in the heap and returns a reference to the closure on top of the stack.

We start with the code schemata for the first two kinds:

108

The instruction  $\text{new}(tag, args)$  creates a corresponding object  $(B, C, F, V)$  in  $H$  and returns a reference to it.

We distinguish three different kinds of code for an expression  $e$ :

- $\text{code}_V e$  — (generates code that) computes the **V**alue of  $e$ , stores it in the heap and returns a reference to it on top of the stack (the normal case);
- $\text{code}_B e$  — computes the value of  $e$ , and returns it on the top of the stack (only for **B**asic types);
- $\text{code}_C e$  — does **not** evaluate  $e$ , but stores a **C**losure of  $e$  in the heap and returns a reference to the closure on top of the stack.

We start with the code schemata for the first two kinds:

108

### 13 Simple expressions

Expressions consisting only of constants, operator applications, and conditionals are translated like expressions in imperative languages:

$$\begin{aligned} \text{code}_B b \rho \text{sd} &= \text{loadc } b \\ \text{code}_B (\square_1 e) \rho \text{sd} &= \text{code}_B e \rho \text{sd} \\ &\quad \text{op}_1 \\ \text{code}_B (e_1 \square_2 e_2) \rho \text{sd} &= \text{code}_B e_1 \rho \text{sd} \\ &\quad \text{code}_B e_2 \rho (\text{sd} + 1) \\ &\quad \text{op}_2 \end{aligned}$$

109

$$\begin{aligned} \text{code}_B (\text{if } e_0 \text{ then } e_1 \text{ else } e_2) \rho \text{sd} &= \text{code}_B e_0 \rho \text{sd} \\ &\quad \text{jumpz } A \\ &\quad \text{code}_B e_1 \rho \text{sd} \\ &\quad \text{jump } B \\ A: &\quad \text{code}_B e_2 \rho \text{sd} \\ B: &\quad \dots \end{aligned}$$

110

### Note:

- $\rho$  denotes the actual **address environment**, in which the expression is translated.
- The extra argument **sd**, the **stack difference**, *simulates* the movement of the **SP** when instruction execution modifies the stack. It is needed later to address variables.
- The instructions **op<sub>1</sub>** and **op<sub>2</sub>** implement the operators  $\square_1$  and  $\square_2$ , in the same way as the operators **neg** and **add** implement negation resp. addition in the **CMA**.
- For all other expressions, we first compute the value in the heap and then dereference the returned pointer:

$$\text{code}_B e \rho \text{sd} = \text{code}_Y e \rho \text{sd} \\ \text{getbasic}$$

111

## 13 Simple expressions

Expressions consisting only of constants, operator applications, and conditionals are translated like expressions in imperative languages:

$$\begin{aligned} \text{code}_B b \rho \text{sd} &= \text{loadc } b \\ \text{code}_B (\square_1 e) \rho \text{sd} &= \text{code}_B e \rho \text{sd} \\ &\quad \text{op}_1 \\ \text{code}_B (e_1 \square_2 e_2) \rho \text{sd} &= \text{code}_B e_1 \rho \text{sd} \\ &\quad \text{code}_B e_2 \rho (\text{sd} + 1) \\ &\quad \text{op}_2 \end{aligned}$$

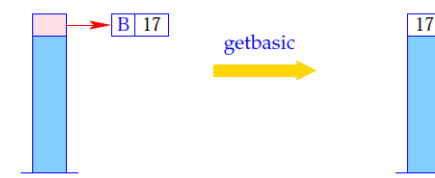
109

### Note:

- $\rho$  denotes the actual **address environment**, in which the expression is translated.
- The extra argument **sd**, the **stack difference**, *simulates* the movement of the **SP** when instruction execution modifies the stack. It is needed later to address variables.
- The instructions **op<sub>1</sub>** and **op<sub>2</sub>** implement the operators  $\square_1$  and  $\square_2$ , in the same way as the operators **neg** and **add** implement negation resp. addition in the **CMA**.
- For all other expressions, we first compute the value in the heap and then dereference the returned pointer:

$$\text{code}_B e \rho \text{sd} = \text{code}_Y e \rho \text{sd} \\ \text{getbasic}$$

111



```
if (H[S[SP]] != (B,_))
  Error "not basic!";
else
  S[SP] = H[S[SP]].v;
```

112



For `codeV` and simple expressions, we define analogously:

$$\begin{aligned}
 \text{code}_V b \rho \text{ sd} &= \text{loadc } b; \text{mkbasic} \\
 \text{code}_V (\square_1 e) \rho \text{ sd} &= \text{code}_B e \rho \text{ sd} \\
 &\quad \text{op}_1; \text{mkbasic} \\
 \text{code}_V (e_1 \square_2 e_2) \rho \text{ sd} &= \text{code}_B e_1 \rho \text{ sd} \\
 &\quad \text{code}_B e_2 \rho (\text{sd} + 1) \\
 &\quad \text{op}_2; \text{mkbasic} \\
 \text{code}_V (\text{if } e_0 \text{ then } e_1 \text{ else } e_2) \rho \text{ sd} &= \text{code}_B e_0 \rho \text{ sd} \\
 &\quad \text{jumpz } A \\
 &\quad \text{code}_V e_1 \rho \text{ sd} \\
 &\quad \text{jump } B \\
 A: &\text{code}_V e_2 \rho \text{ sd} \\
 B: &\dots
 \end{aligned}$$

113

For `codeV` and simple expressions, we define analogously:

$$\begin{aligned}
 \text{code}_V b \rho \text{ sd} &= \text{loadc } b; \text{mkbasic} \\
 \text{code}_V (\square_1 e) \rho \text{ sd} &= \text{code}_B e \rho \text{ sd} \\
 &\quad \text{op}_1; \text{mkbasic} \\
 \text{code}_V (e_1 \square_2 e_2) \rho \text{ sd} &= \text{code}_B e_1 \rho \text{ sd} \\
 &\quad \text{code}_B e_2 \rho (\text{sd} + 1) \\
 &\quad \text{op}_2; \text{mkbasic} \\
 \text{code}_V (\text{if } e_0 \text{ then } e_1 \text{ else } e_2) \rho \text{ sd} &= \text{code}_B e_0 \rho \text{ sd} \\
 &\quad \text{jumpz } A \\
 &\quad \text{code}_V e_1 \rho \text{ sd} \\
 &\quad \text{jump } B \\
 A: &\text{code}_V e_2 \rho \text{ sd} \\
 B: &\dots
 \end{aligned}$$

113

## 14 Accessing Variables

We must distinguish between **local** and **global** variables.

**Example:** Regard the function  $f$ :

$\text{let } c = 5$   
 $\text{in let } f = \text{fun } a \rightarrow \text{let } b = a$   
 $\text{in } b + c$   
 $\text{in } f \ c$

The function  $f$  uses the **global** variable  $c$  and the **local** variables  $a$  (as formal parameter) and  $b$  (introduced by the inner `let`).

The binding of a global variable is determined, when the function is **constructed** (**static scoping!**), and later only looked up.

115